



Ocean Products and Atmospheric Removal in APS

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February 22, 2011

Outline


- 1. Data Processing in the Automated Processing System (APS)**
2. HICO processing streams in APS
3. Vicarious Calibration in APS
4. HICO APS Data Products
5. HICO APS Data Processed through HOPE Algorithm
6. Summary

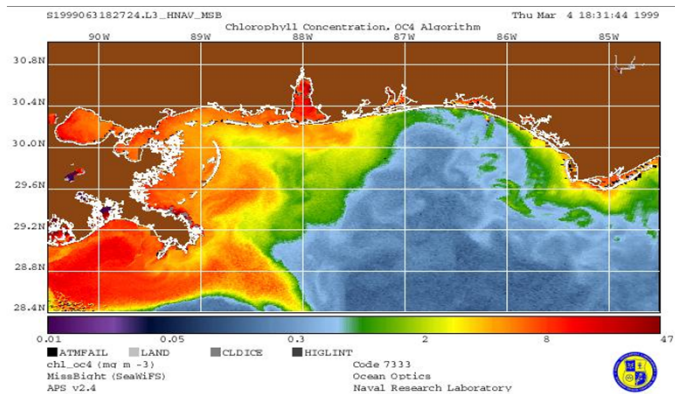
Automated Processing System (APS)

The Automated Processing System (APS) is a collection of UNIX programs and shell scripts designed to generate regional map-projected image data bases of satellite derived bio-optical products from a large flow of raw satellite input data in an automated fashion.

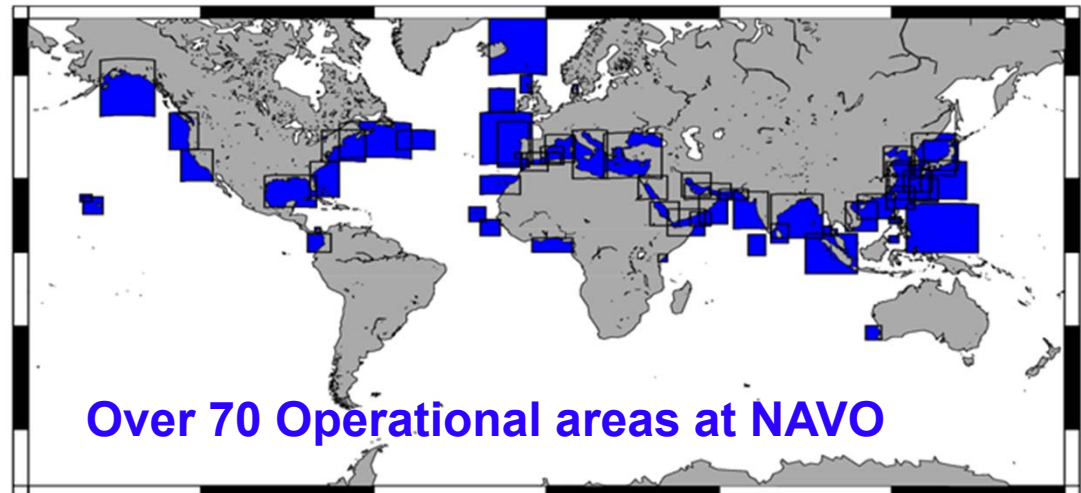
- Consistent with standard NASA processing code (SeaDAS 6.1) for SeaWiFS, MODIS, MERIS.
- Addition of Navy-specific algorithms and products (absorption, backscattering coefficients, diver visibility).
- No graphical user interface.
- Multiple platforms (Linux RH 7.1, RH 7.3/SGI IRIX 6.5).
- An SQL database is populated (web browsing).

APS Development

- Developed at NRL/Stennis
- End-to-end processing (radiometric, atmospheric, geometric correction  optical products) within several minutes
- Handles multiple satellites, algorithms, regions-of-interest
- Multiple input streams: NRL receiving system, NOAA, NASA – real time and archival data (global)
- Adding new products, sensors (euphotic depth, MERIS, HICO)
- Architecture in place to easily test algorithms, reprocess large imagery data bases



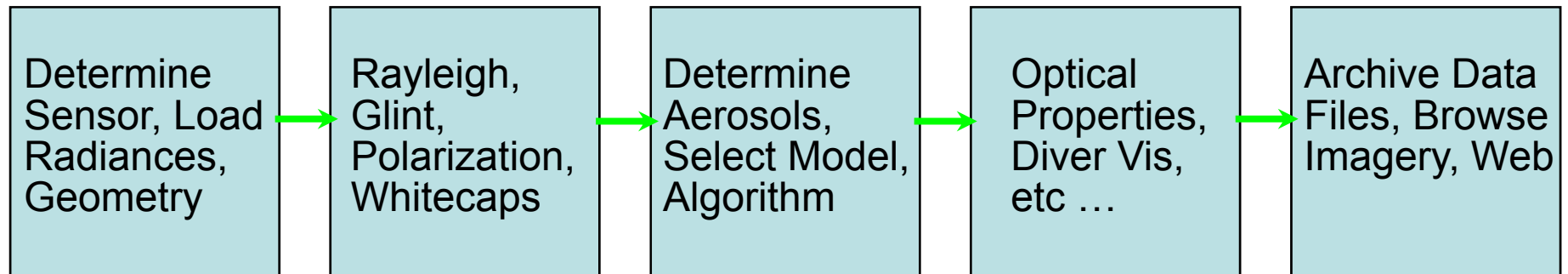
- *weekly, monthly composites*
- *data files*
- *browse imagery*



Data Transformation in APS

- Individual scenes are sequentially processed from the raw digital counts (Level-1) to radiometrically, atmospherically, and geometrically corrected (Level-3) products within several minutes.
- Data processed into several temporal (daily, 8-day, monthly, and yearly) composites or averages (Level-4).
- Quick-look “browse” images (PNG) are automatically generated and stored on a web.
- The Level-3 and Level-4 data (HDF v4) are archived in a directory-based data base that resides on a 40TB RAID array.

APS Processing Steps



multiple atmospheric correction schemes, aerosol models

Ocean Color Imagery

- **Multi-Year Image Archive**

SeaWiFS - 1km, daily, 1997-present

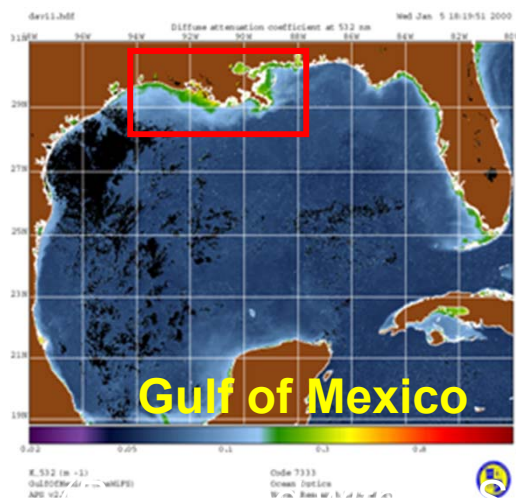
MODIS - 250m, 500m and 1 km, daily, 2002-present

OCM – 350m, 8 bands

MERIS – 1km (300m), 15 bands

- **Processed With Consistent Algorithms**

**Daily, Weekly, Monthly
Bio-Optical Properties
1 km resolution**



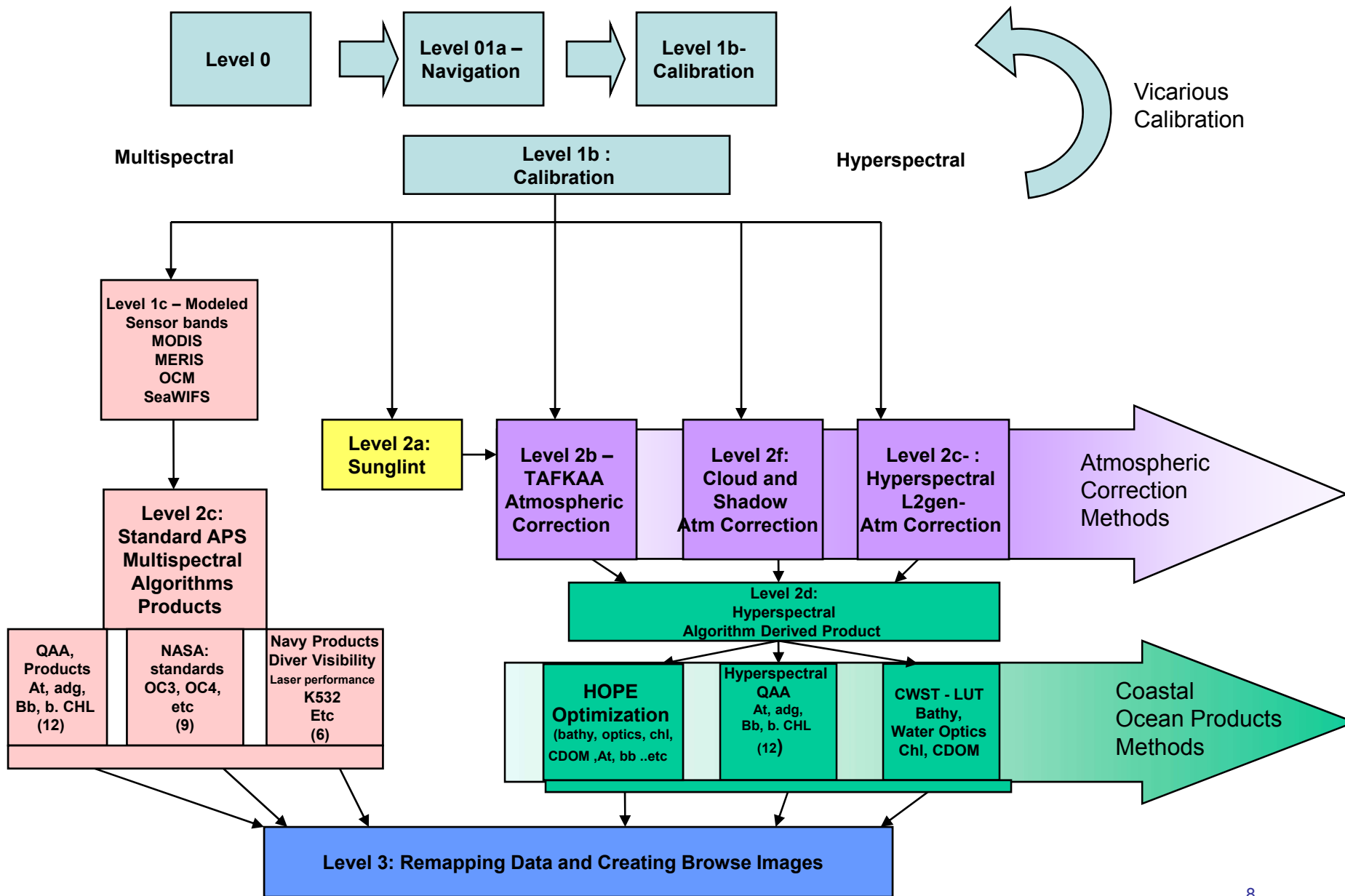
Bio-Optical Properties

- Radiances, Reflectances
- Chlorophyll
- Partitioned Absorption Coefficients (*detrital, sediment, CDOM, and phytoplankton*)
- Backscattering Coefficient
- Diffuse, Beam Attenuation Coefficients
- Suspended Particulate Concentrations (*total, organic, inorganic*)
- Euphotic Depth
- Diver Visibility

Outline

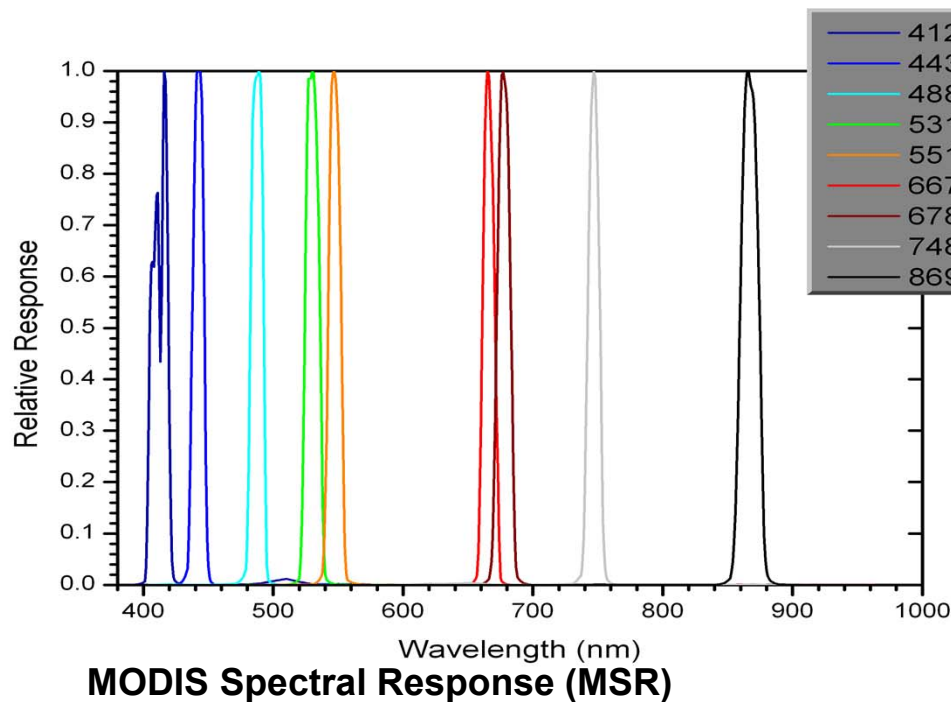
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HICO Processing Activity in APS



MODIS-like (Multispectral) HICO Data Creation

- Perform convolution over 412, 443, 488, 531, 547, 667, 678, 748, 869 nmeter MODIS Aqua spectral response
- Generate 9 band data set and store within simple format and also envi file format
- Write data readers for APS to ingest data into APS
- Process according using usual MODIS processing algorithms
- Compare products to MODIS derived products



Band Convolution performed by:

$$\text{ML HICO}_i = \frac{\sum \text{MSR}_{jk} * \text{HICO_data}_k}{\sum \text{MSR}_{jk}}$$

ML HICO_i : MODIS-Like HICO data for *ith* MODIS band
HICO_data_k : Hyperspectral data for *kth* wavelength
MSR_{ik} : MODIS Spectral Response for *ith* MODIS band and *kth* wavelength

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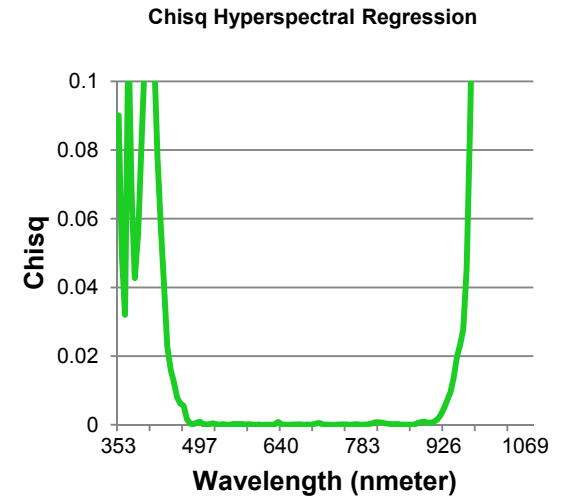
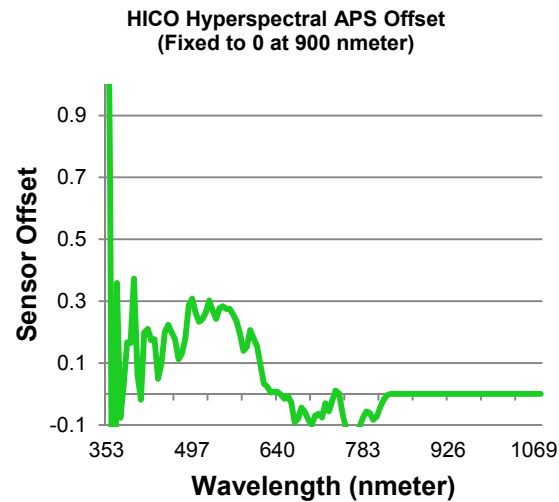
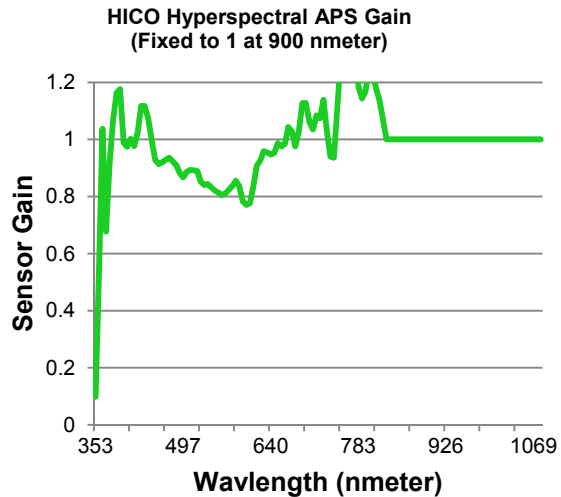
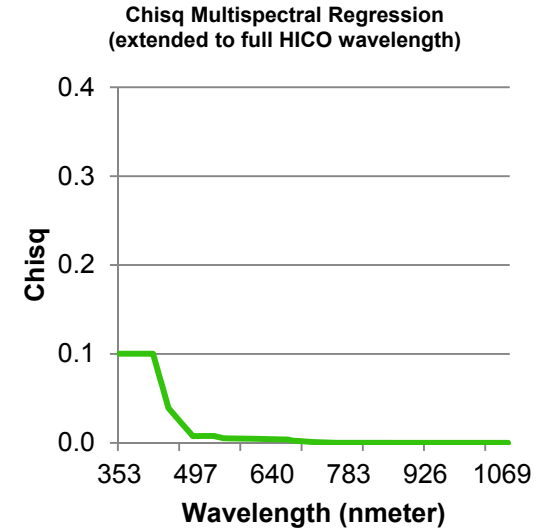
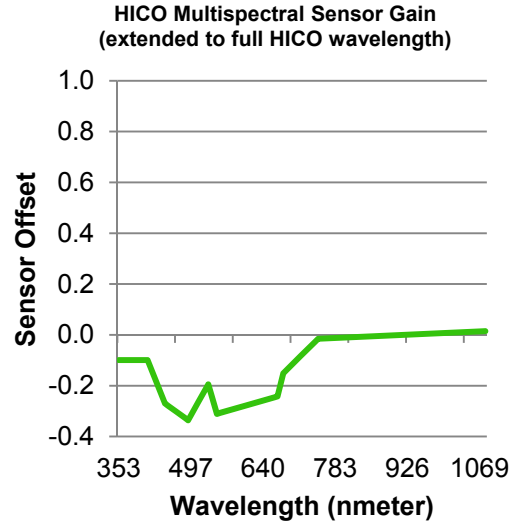
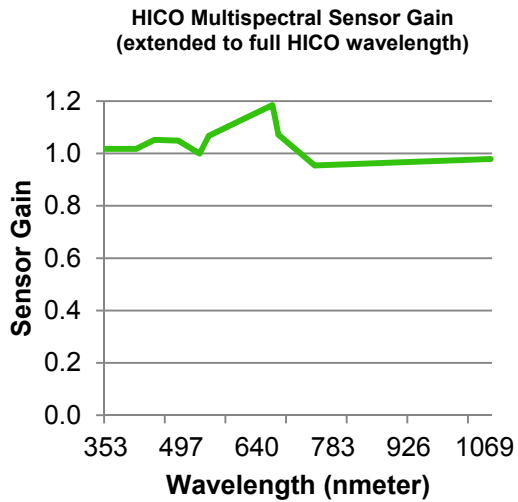
Vicarious Calibration Option in APS

- Purpose is to fit nLw computed by APS to in situ data
 - Sensor gains/offsets unique for NIR atmospheric correction of APS
 - Also unique to parameters used (designated wavelengths, etc)
- Forward atmospheric correction computation
 - Perform standard atmospheric correction over in situ site
 - Store rayleigh/aerosol radiances and absorption terms
 - Compute normalized water leaving radiance (nLw)
- Inversion of atmospheric correction
 - Substitute in situ (nLw) into level 2 nLw record
 - Add computed atmospheric terms to in situ nLw to get vicarious Lt
 - Vicarious Lt is the Lt value needed to compute in situ nLw
 - Store original Lt and vicarious Lt values
- Linear regression over sample sites generates sensor gains/offsets

Vicarious Calibration Activity

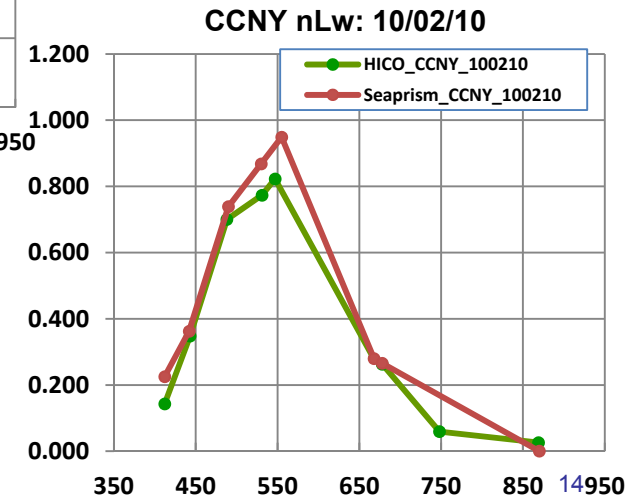
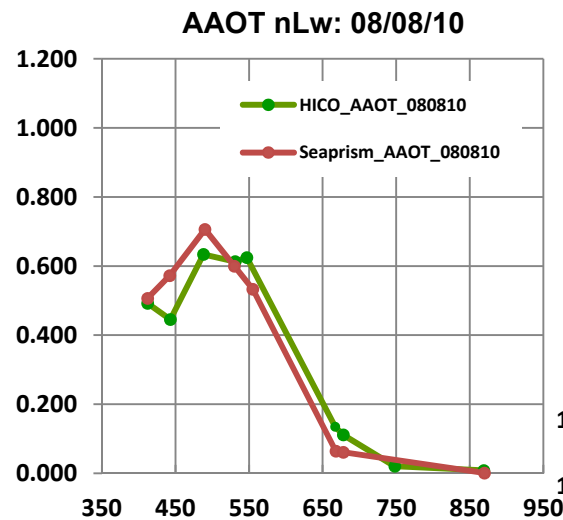
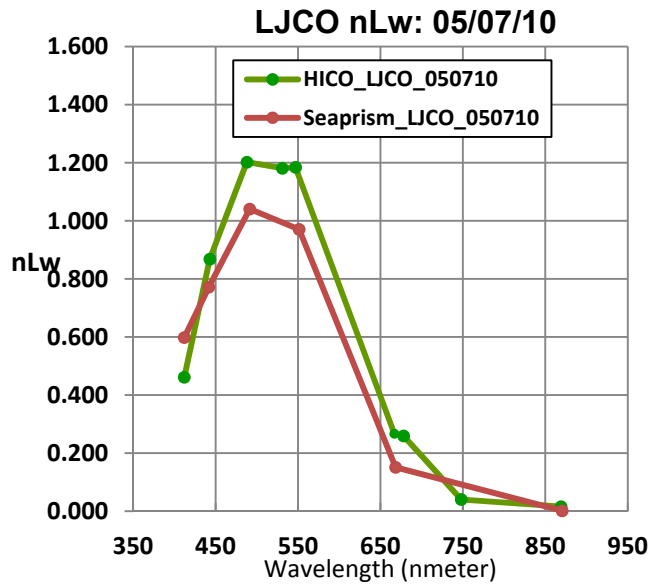
- Multispectral (MODIS-Like) HICO Data
 - 7 Aeronet sites (Seaprism data) included AAOT, LISCO, LJCO locations from 12/10/09 to 10/02/10
 - Seaprism data interpolated for MODIS 531nm and 678nm bands
- Hyperspectra Data
 - 3 LISCO (Hypersas) dates included from Sep/Oct 2010
 - Hypersas data interpolated to HICO wavelengths
- Common processing
 - vLt values computed by APS inverse atmospheric correction
 - Measured Lt and vLt stored
 - Vicarious gains and offsets set by linear regression of Lt to vLt

Vicariously Calibrated Gain/Offset Values



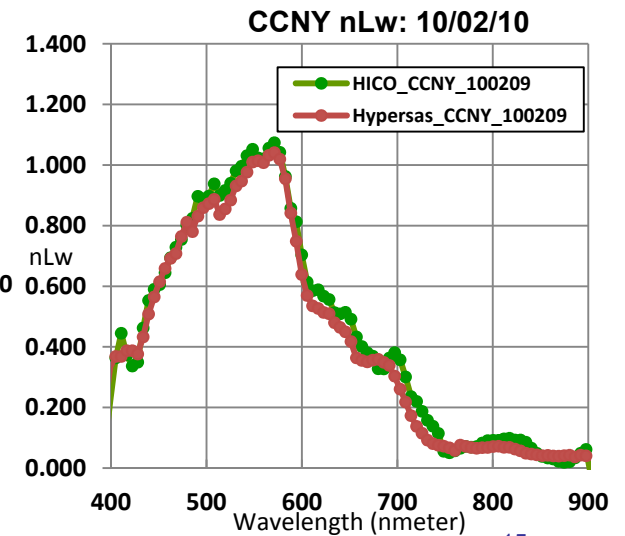
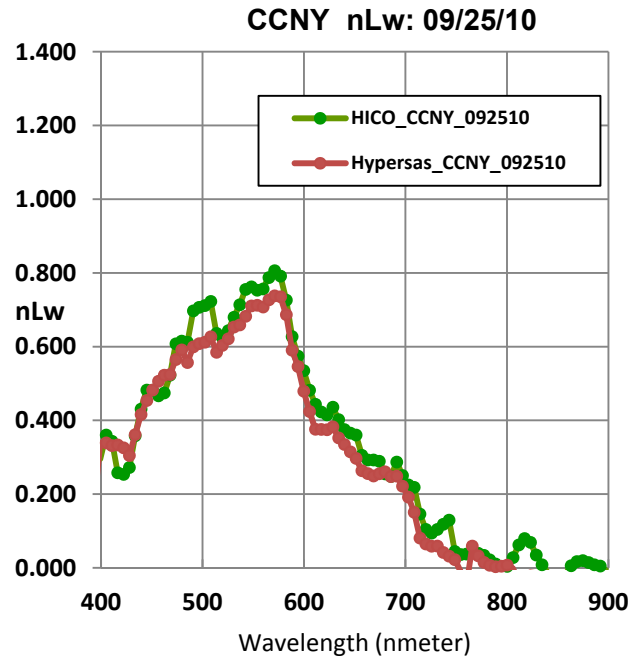
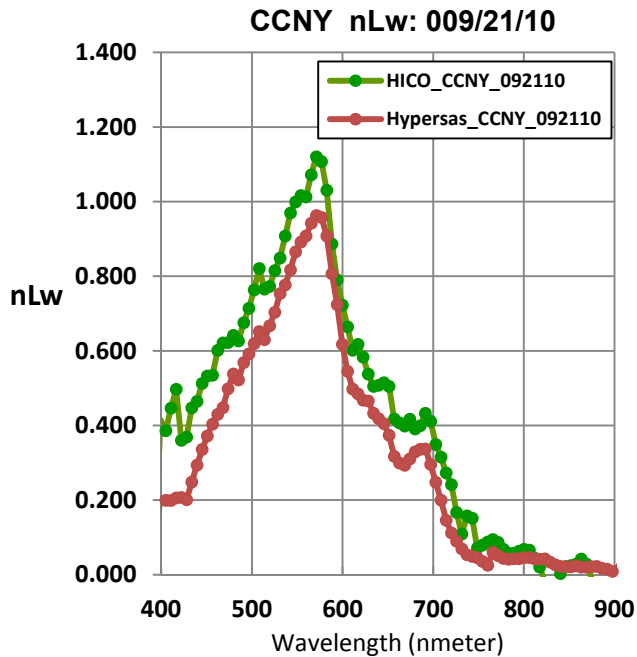
Multispectral Vicarious Gain Validation

- Data reprocessed with new sensor gain/offsets
- APS processed HICO spectral overlaid on in situ data for comparison



Hyperpectral Vicarious Gain Validation

- Data reprocessed with new sensor gain/offsets
- APS processed HICO spectral overlaid on in situ data for comparison



Vicarious Calibration Activity Summary

- 7 MODIS-like HICO (9 band) scenes in multispectral study
- 3 HICO scenes in hyperspectral study
- In Situ AERONET data used to compute vicarious L_t values
- Linear regression between HICO measured L_t and vicarious L_t values used to set gains and offsets
- Scenes reprocessed with new gains/offsets to determine new nL_w at AERONET location
- Results unique to APS atmospheric correction inputs

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Hong Kong, 2 October 2009

True Color

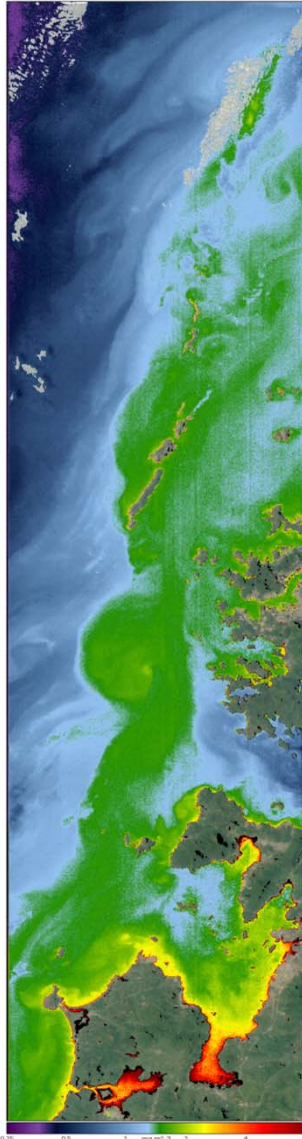
iss.2009275.1002.004850.L1B Hong_Kong_China.v02.1F01 Oct 2 00 41 03 2009
True Color Image



True_color
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
SeaWiFS Space Center MS

Chlorophyll (oc3)

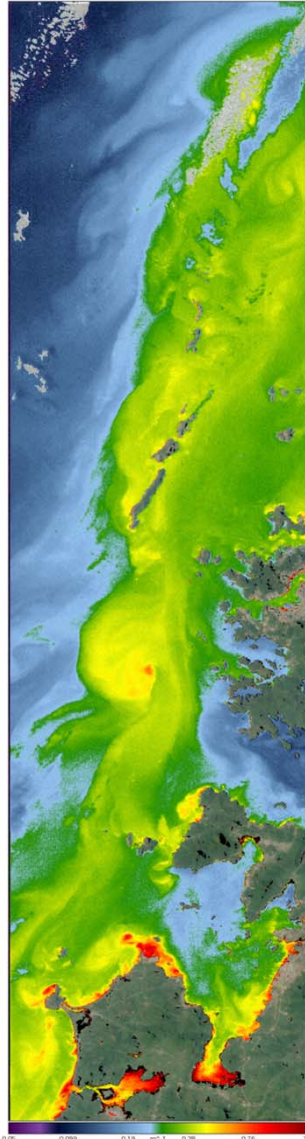
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Chlorophyll Concentration, OC3 Algorithm



oc3
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
SeaWiFS Space Center MS

K_d (488)

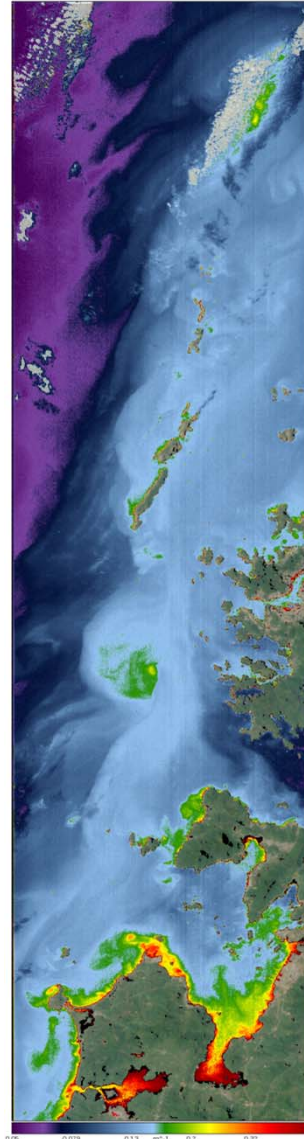
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Diffuse attenuation at 488 nm, Lee algorithm



K_d_{488}
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
SeaWiFS Space Center MS

a (443)

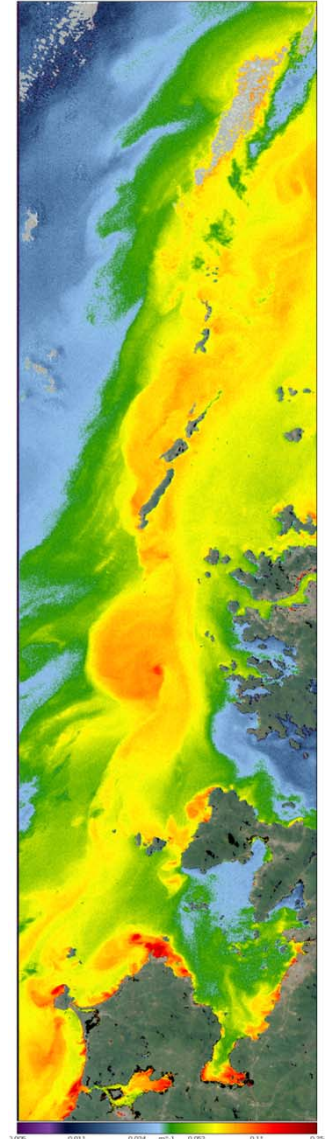
iss.2009275.1002.004850.L1B Hong_Kong_China.v02.1F01 Oct 2 00 41 03 2009
Total absorption at 443 nm, QAA algorithm v5



a_{443}
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
SeaWiFS Space Center MS

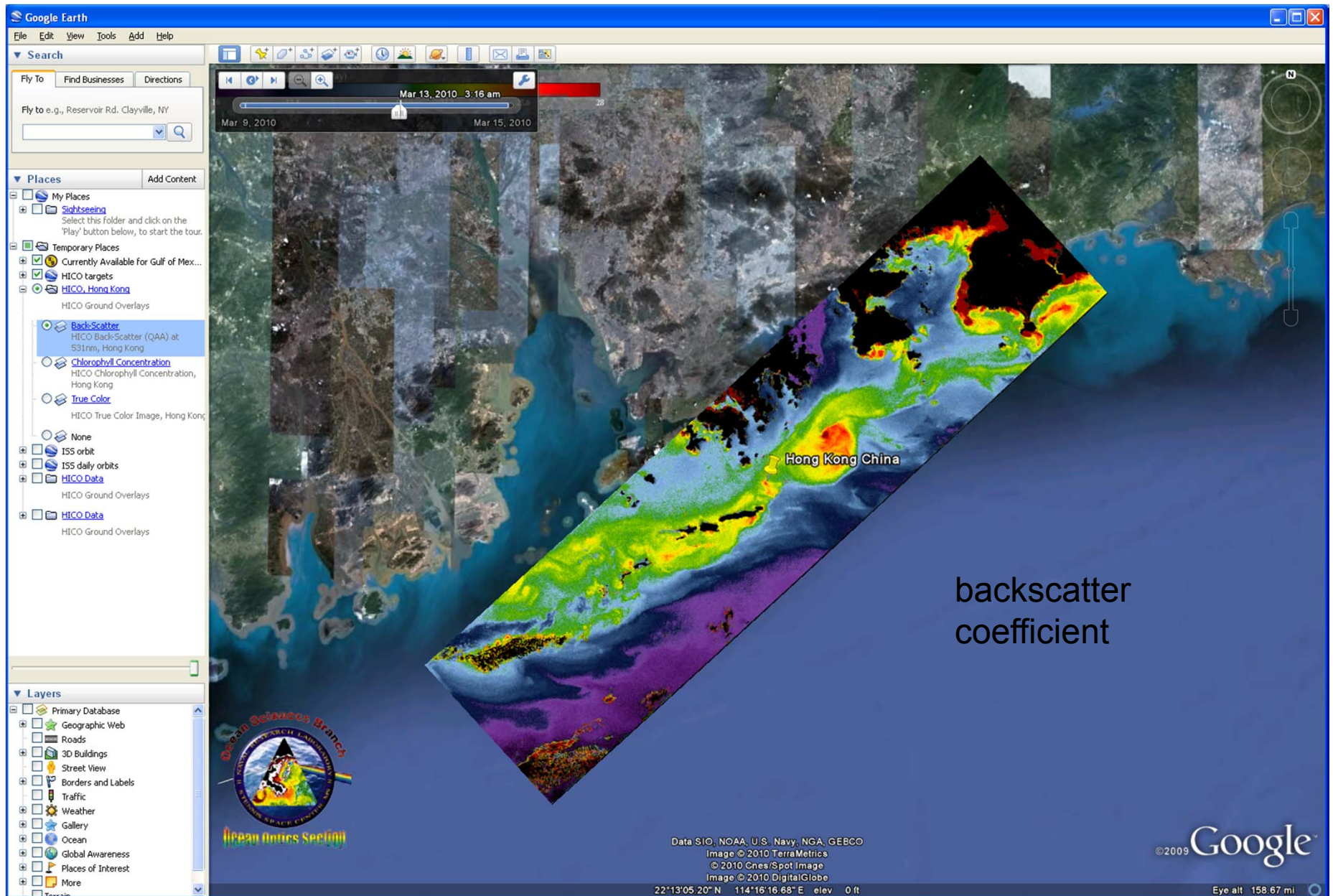
b_b (488)

iss.2009275.1002.004850.L1B Hong_Kong_China.v02.1F01 Oct 2 00 41 03 2009
Total backscatter at 488 nm, QAA algorithm v5



b_{b488}
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
SeaWiFS Space Center MS

Hong Kong: 10/02/09: HICO Products over Google Earth Background



backscatter
coefficient

Hong Kong, 2 October 2009

True Color

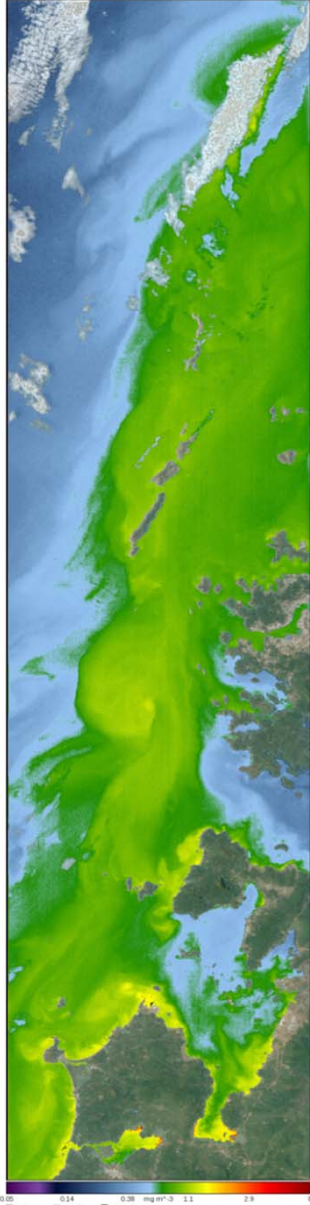
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True Color Image



True_color
Sensor Frame
Code: 7330/Ocean Sciences
Naval Research Laboratory
Bermis Space Center, MS

Chlorophyll (oc3)

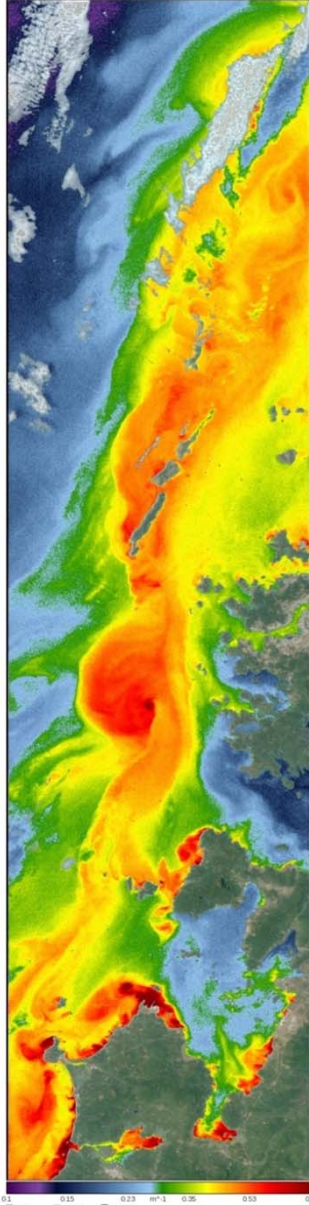
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Chlorophyll Concentration, OC3 Algorithm



oc3
LAND CLDICE ATMPL
0.02 0.14 0.38 mg m⁻³ 1.1 2.9
Code: 7330/Ocean Sciences
Naval Research Laboratory
Bermis Space Center, MS

K_d (488)

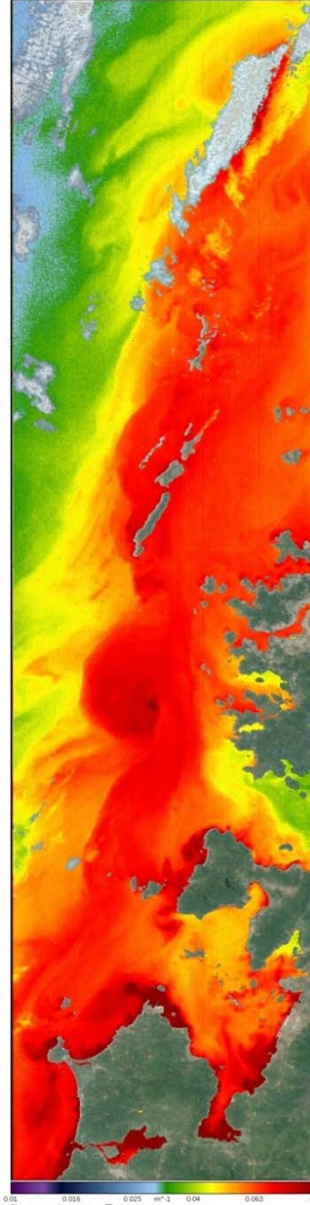
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Diffuse attenuation at 488 nm, Lee algorithm



Kd
LAND CLDICE ATMPL
0.1 0.15 0.23 m⁻¹ 0.35 0.53
Code: 7330/Ocean Sciences
Naval Research Laboratory
Bermis Space Center, MS

a (443)

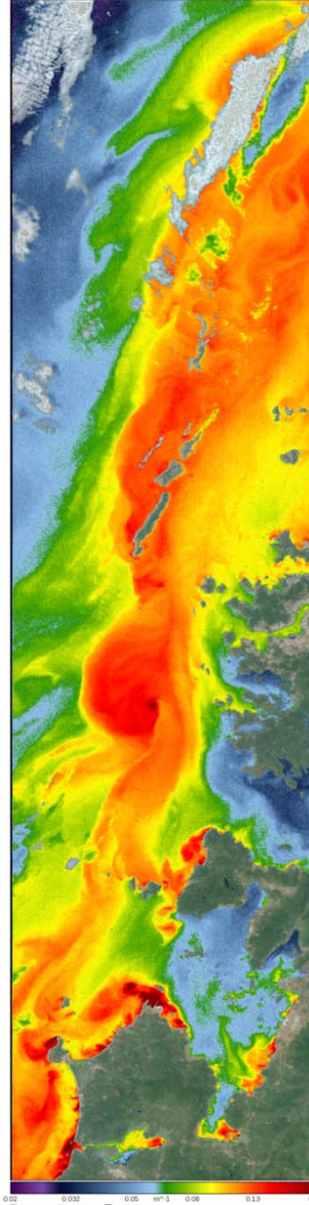
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Total absorption at 443 nm, QAA algorithm v5



a
LAND CLDICE ATMPL
0.05 0.018 0.025 m⁻¹ 0.04 0.063 0.1
Code: 7330/Ocean Sciences
Naval Research Laboratory
Bermis Space Center, MS

b_b (488)

iss-2009275.1002.004050.L1B.Hong_Kong_China.v02.1F01.Oct.2.00.41.03.2009
Total backscatter at 488 nm, QAA algorithm v5



b_b
LAND CLDICE ATMPL
0.02 0.002 0.05 m⁻¹ 0.08 0.13
Code: 7330/Ocean Sciences
Naval Research Laboratory
Bermis Space Center, MS

Bahrain, 18 November 2009

True Color

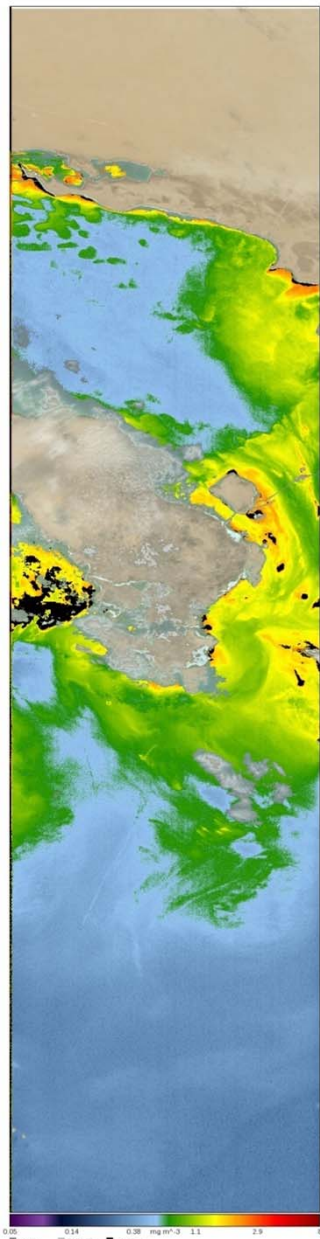
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True Color image



True_color
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
Stennis Space Center, MS

Chlorophyll (oc3)

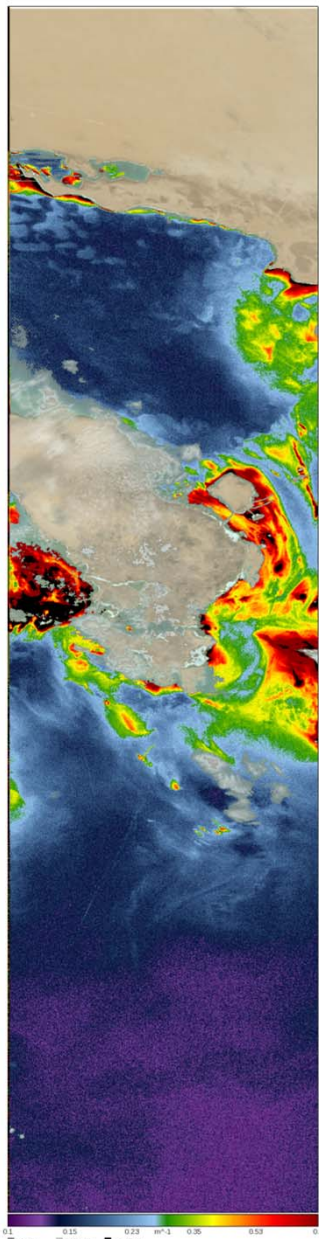
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Chlorophyll Concentration, OC3 Algorithm



oc3
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
Stennis Space Center, MS

K_d (488)

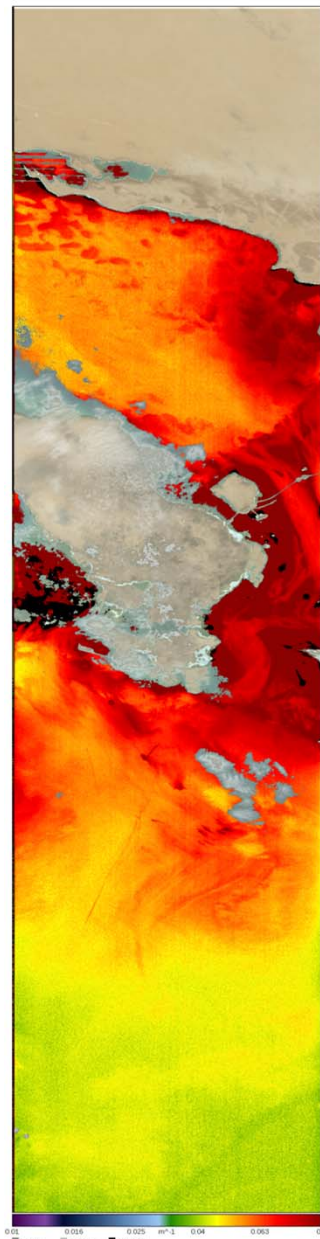
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Diffuse attenuation at 488 nm, Lee algorithm



Kd_488
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
Stennis Space Center, MS

a (443)

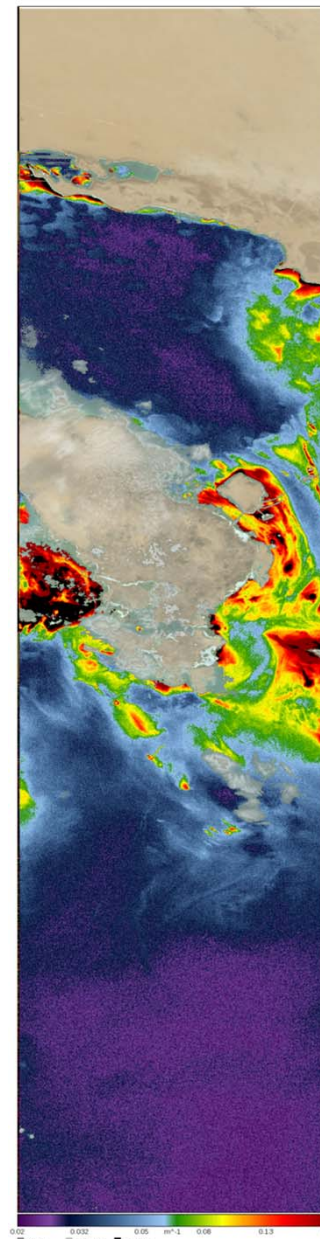
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Total absorption at 443 nm, QAA algorithm v5



a_443
Sensor Frame
Code 7330/Ocean Sciences
Naval Research Laboratory
Stennis Space Center, MS

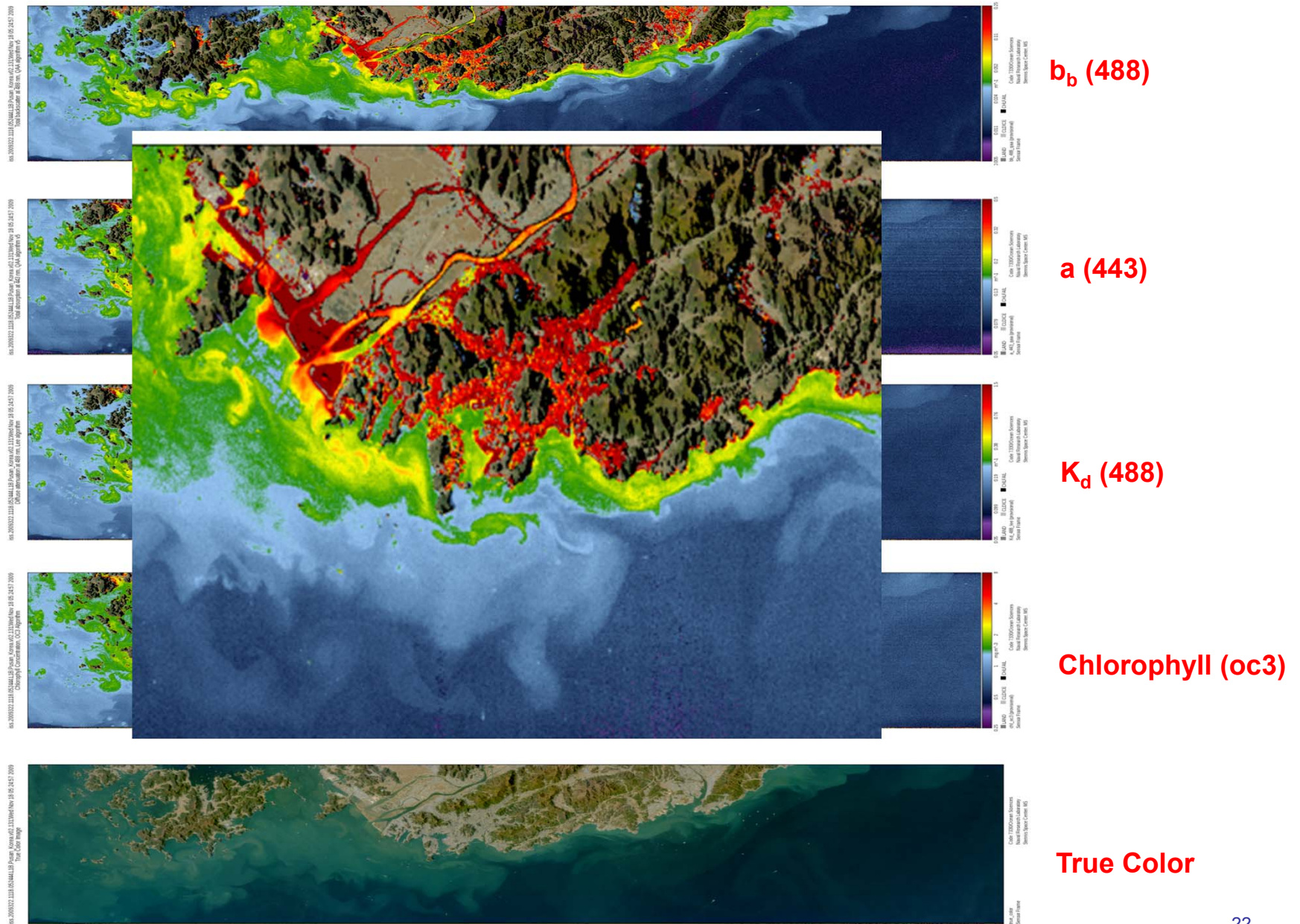
b_b (488)

iss.2009322.1118.095529.L1B Bahrain.v02.1313.200Wed Nov 18 09:55:42 2009
Total backscatter at 488 nm, QAA algorithm v5

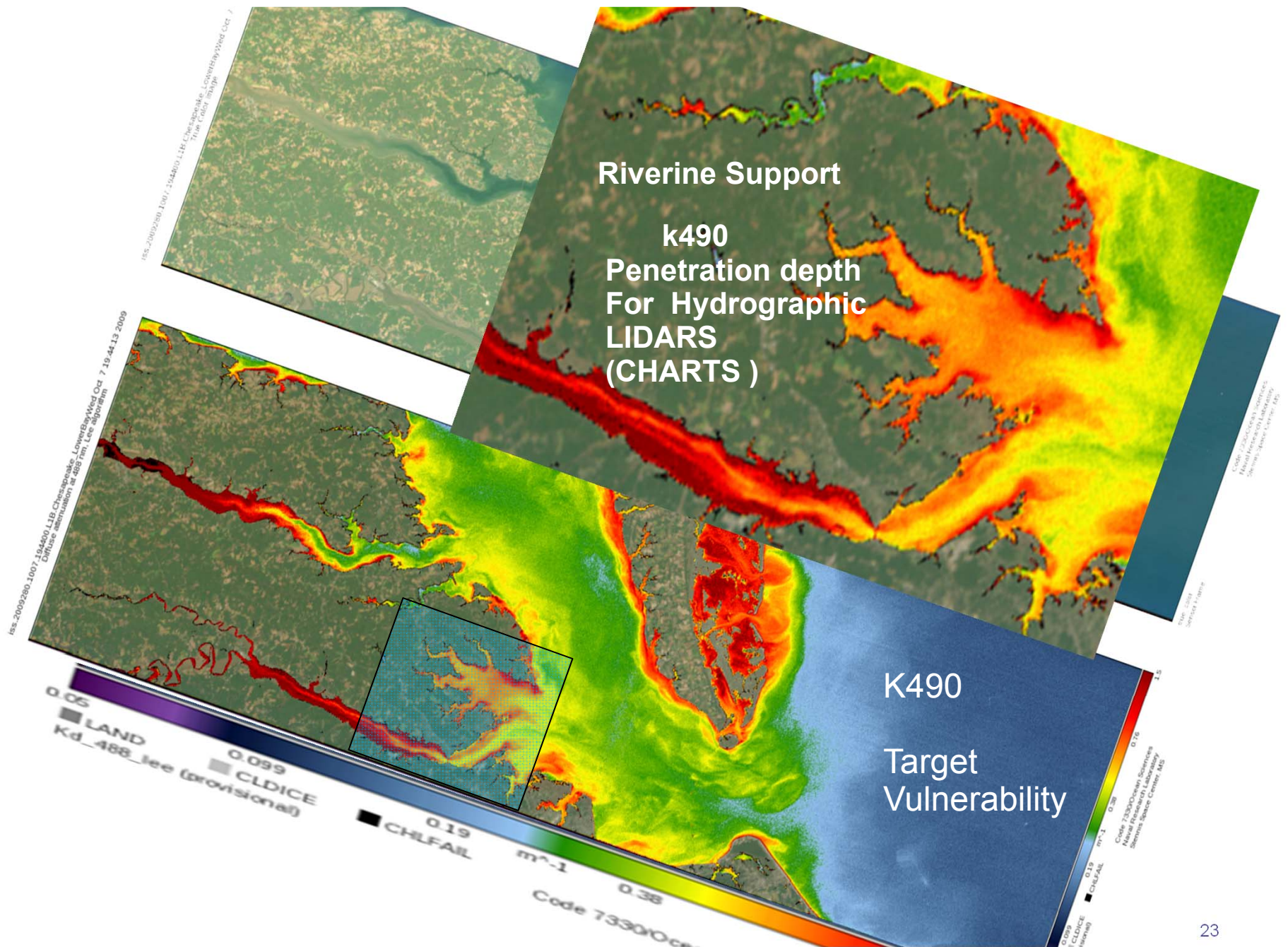


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Naval Research Laboratory
Stennis Space Center, MS

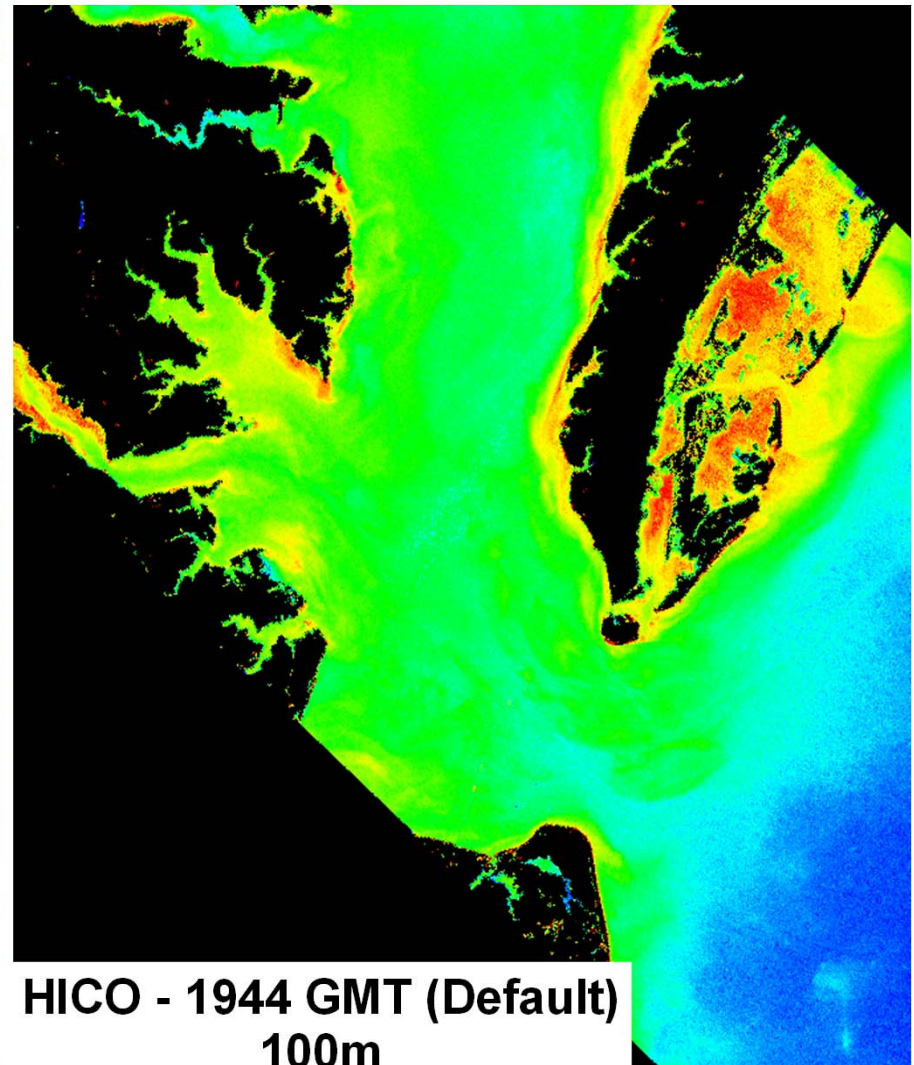
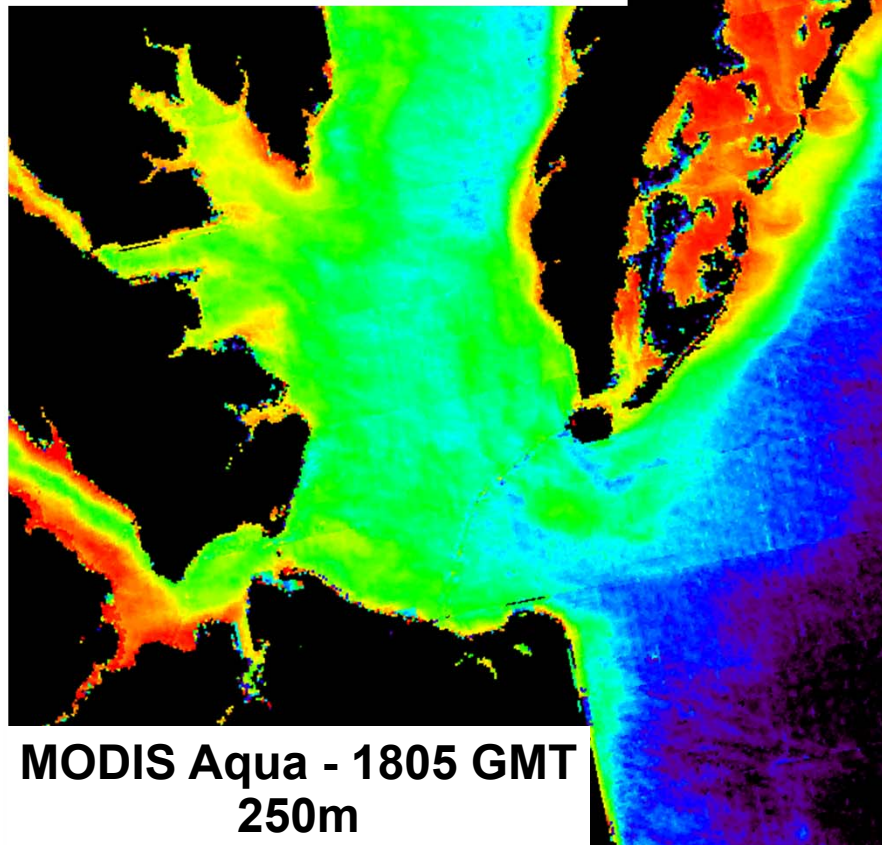
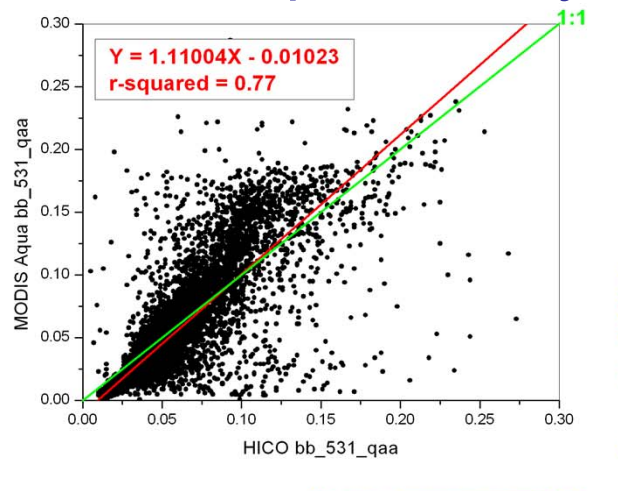
Pusan, Korea, 18 November 2009



Chesapeake Bay: 10/07/09: Diffuse Attenuation

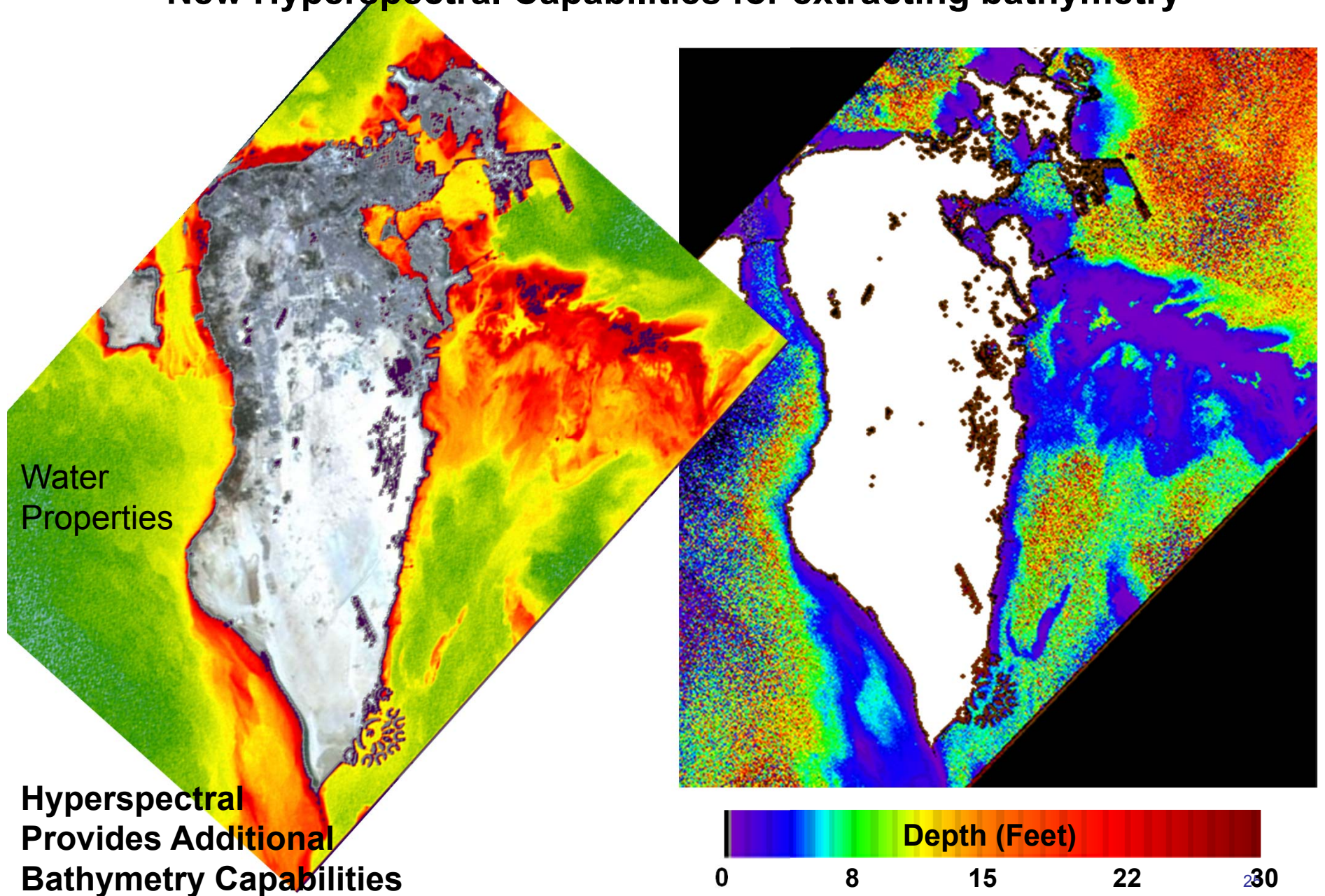


Chesapeake Bay: 10/07/09: Backscatter @ 531nm (QAA)



HICO Image – Bahrain 10/02/09

New Hyperspectral Capabilities for extracting bathymetry



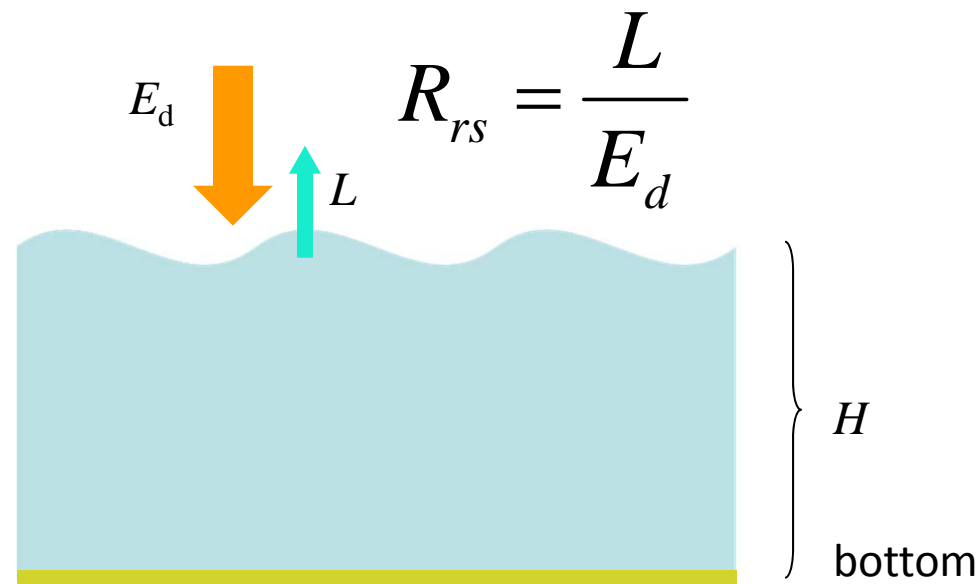
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HOPE Algorithm

1. Some basics of HOPE

(**H**yperspectral **O**ptimization **P**rocess **E**xemplar)



$$R_{rs}(\lambda) = F[\underbrace{a(\lambda), b_b(\lambda)}_{\text{Water property}}, \underbrace{\rho(\lambda), H}_{\text{bottom property}}]$$

Water property

bottom property

HOPE Algorithm

$$R_{rs}(\lambda) = F[a(\lambda), b_b(\lambda), \rho(\lambda), H]$$



Explicit Analytical Function

for water column

for bottom

$$r_{rs} \approx r_{rs}^{dp} \left[1 - e^{-\left(D_0 + 1.03(1 + 2.4u)^{0.5}\right)kH} \right] + \frac{\rho}{\pi} e^{-\left(D_0 + 1.04(1 + 5.4u)^{0.5}\right)kH}$$

$$u = bb / (a + bb), \quad k = a + bb$$

$$D_0 \approx 1/\cos(\theta_{\text{sun}})$$

a: a_w – pure water
 a_ϕ – phytoplankton pigments
 a_g – gelbstoff/detritus

b_b: b_{bw} – pure water/molecules
 b_{bp} – particles

(Lee et al 1998, 1999, from Hydrolight runs)

HOPE Algorithm

Have to know the spectrum shapes for analytical derivation!

Global default parameterization:

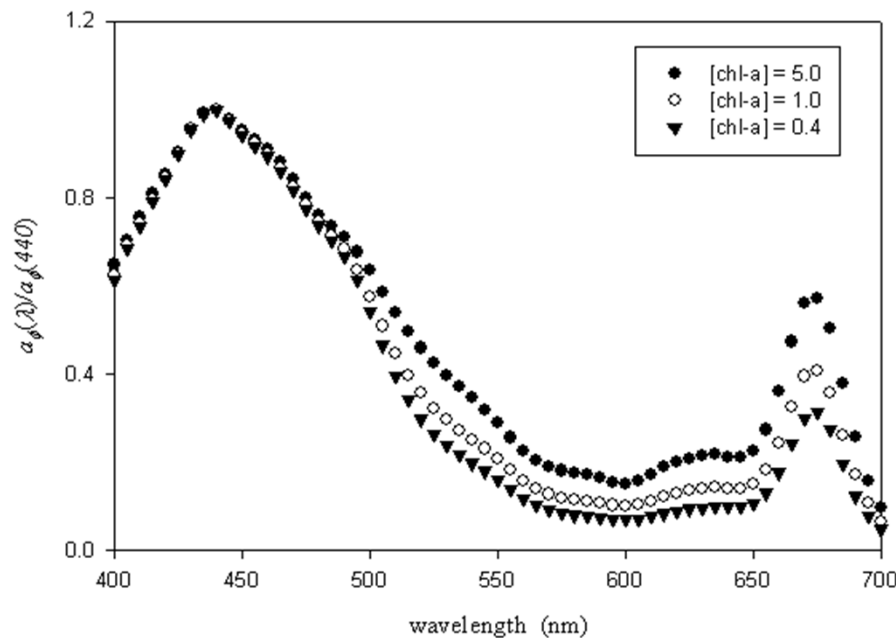
(no access to local information, e.g. Iran, North Korea)

1. Pigment absorption spectrum

$$a_{\phi}(\lambda) = (a_0(\lambda) + a_1(\lambda)\ln(P))P$$

$$P = a_{\phi}(440)$$

$a_0(\lambda)$ and $a_1(\lambda)$ values are available (Lee
1994)



Examples of $a_{\phi}(\lambda)$
simulation.

HOPE Algorithm

Global default parameterization (cont.):

2. CDOM absorption spectrum

$$a_g(\lambda) = \mathbf{G} e^{\frac{-0.015(\lambda-440)}{\lambda}}$$

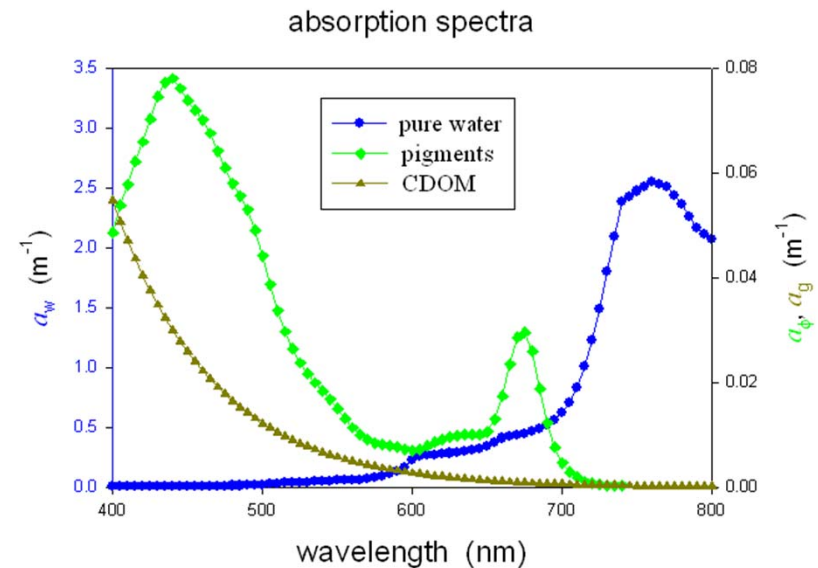
$$\mathbf{G} = a_g(440)$$

3. Particle backscattering spectrum

$$b_{bp}(\lambda) = \mathbf{X} \left(\frac{555}{\lambda} \right)^Y$$

$$\mathbf{X} = b_{bp}(555)$$

$$Y \approx 2.2 \left(1 - 1.2 e^{\frac{-0.9 r_{rs440}}{r_{rs555}}} \right)$$



HOPE Algorithm

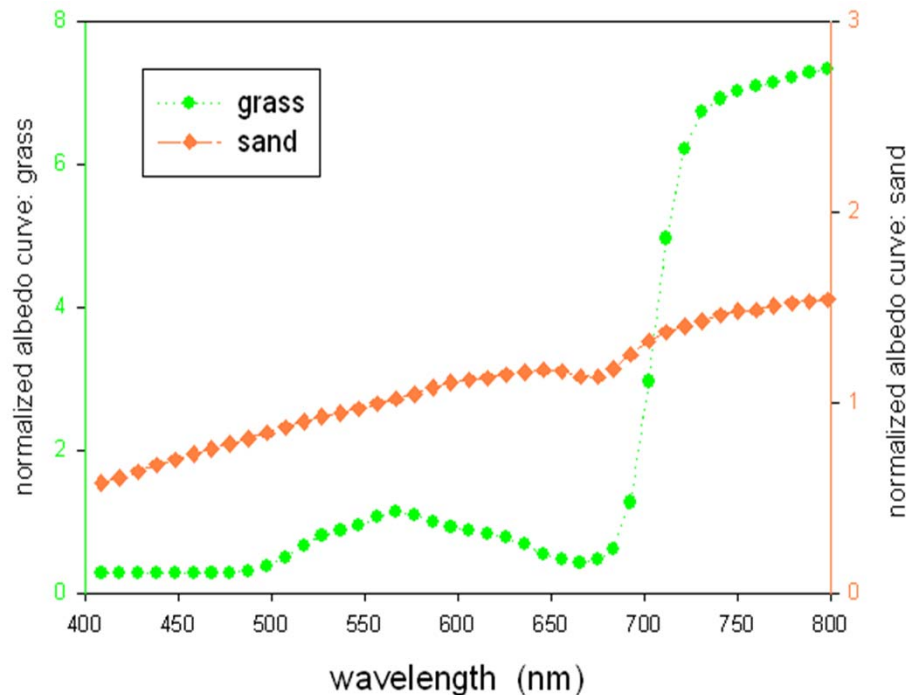
Global default parameterization (cont.):

4. Bottom reflectance spectrum

$$\rho(\lambda) = B * \rho_{bott}^+(\lambda)$$

$\rho_{bott}^+(\lambda) = \rho(\lambda)/\rho(550)$, spectral curvature of bottom reflectance

$$B = \rho(550)$$



Selection criterion:

If $Rrs(550) < 0.01 \text{ sr}^{-1}$

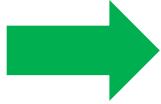
and $Rrs(710)/Rrs(670) > 1.2$,

Grass bottom is assumed;

Otherwise, sandy bottom is assumed.

(Less computation time; less ambiguity)

HOPE Algorithm



$$R_{rs}(\lambda) = F(P, G, X, B, H)$$

Or

$$R_{rs}(\lambda_1) = F(P, G, X, B, H)$$

$$R_{rs}(\lambda_2) = F(P, G, X, B, H)$$

.

.

$$R_{rs}(\lambda_n) = F(P, G, X, B, H)$$

5 unknowns for each $R_{rs}(\lambda)$ spectrum!

HOPE Algorithm

Error function:

$$err = \frac{\left[\sum_{400}^{675} \left(R_{rs} - \hat{R}_{rs} \right)^2 + \sum_{750}^{800} \left(R_{rs} - \hat{R}_{rs} \right)^2 \right]^{0.5}}{\sum_{400}^{675} \hat{R}_{rs} + \sum_{750}^{800} \hat{R}_{rs}} = f(P, G, X, B, H)$$

P, G, X, B and *H* are derived when *err* reaches a minimum (HOPE).

Initial values for HOPE:

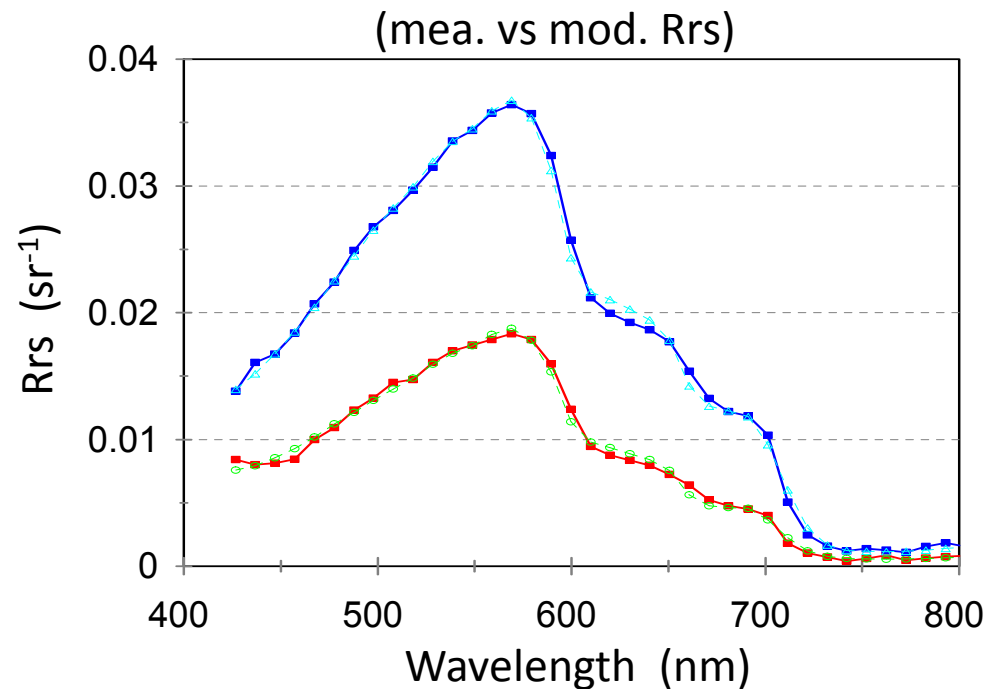
$$P = 0.05 (R_{rs}(443)/R_{rs}(555))^{-1.7}$$

$$G = 1.5 P$$

$$X = 8 R_{rs}(660)$$

$$B = 4 R_{rs}(490)$$

$$H = 1/(6.5 P)$$

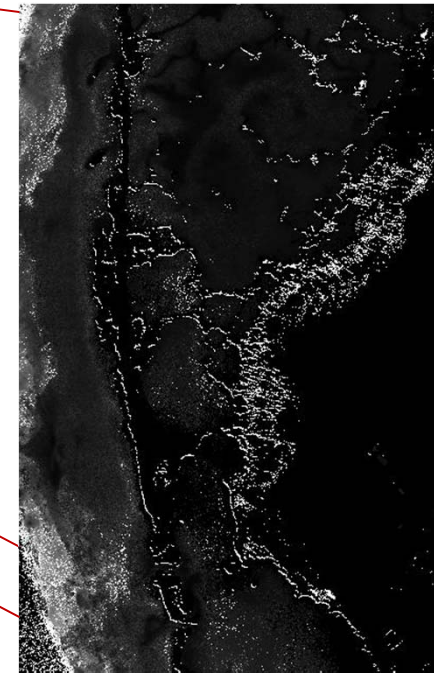


Key Largo HOPE Bathymetry Estimation using HICO

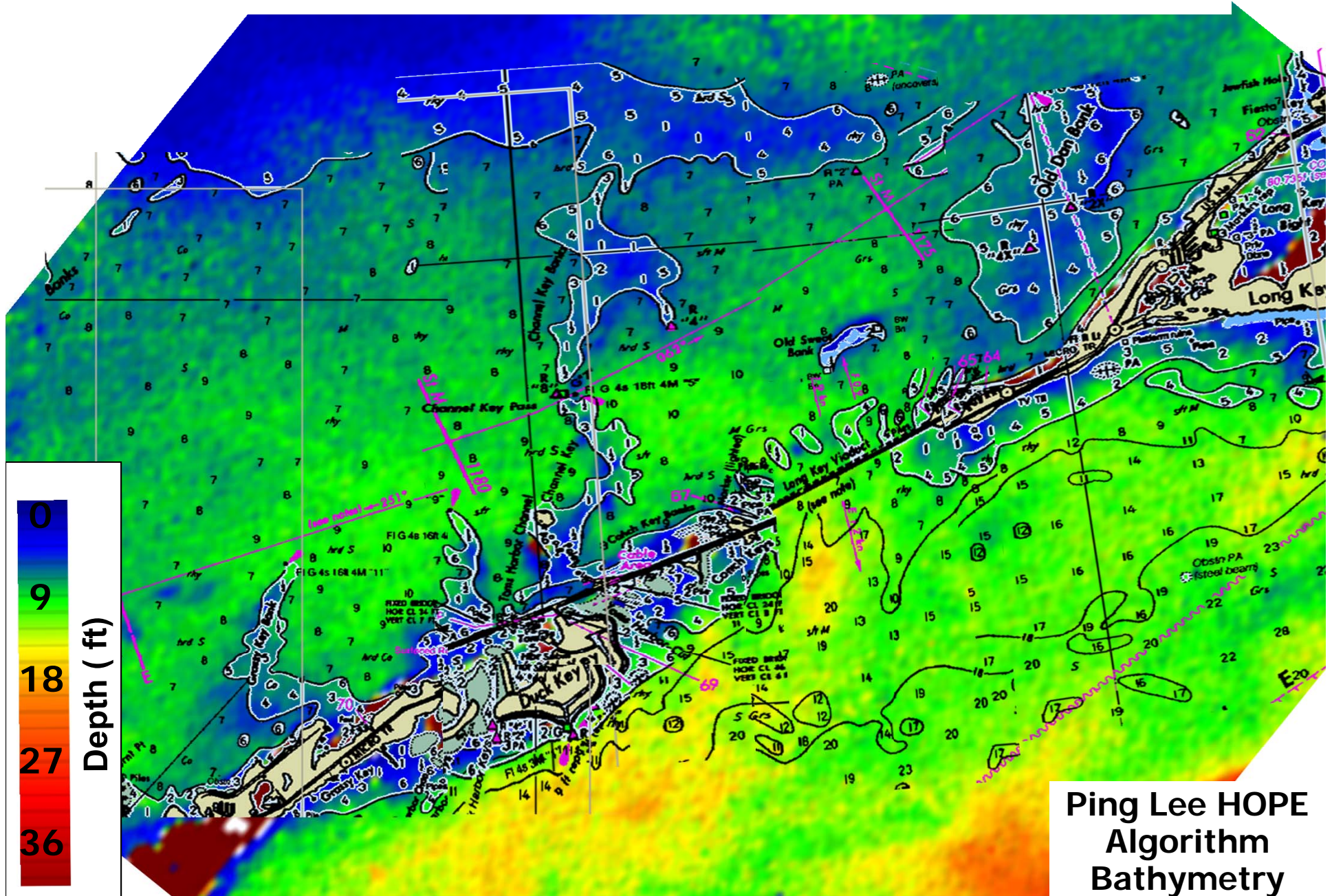
Key Largo 11/13/2009



Bathymetry Estimates
from HOPE Algorithm



HICO Image - Key Largo, Florida: 11/13/09



Summary

- MODIS-Like (multispectral) data set is convolved from MODIS SRF and full hyperspectral HICO data set
- APS has been modified to process multispectral and hyperspectral HICO data
- Vicarious Calibration activity is being explored to refine Level 1B data to APS atmospheric correction method
- APS processed HICO data when received at NRL-SSC
- HICO APS has been processed through HOPE algorithm for parameters including bathymetry