Quantifying uncertainty via machine learning models in aquatic remote sensing

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Outline

- 1. Why do we use Machine Learning (ML) for aquatic remote sensing?
- 2. Why is the uncertainty estimation important in ML?
- 3. What are Mixture Density Networks (MDNs)? How to perform uncertainty estimation for MDNs?
- 4. Do ML estimated uncertainty metrics need calibration?
- 5. How do MDN-derived uncertainties appear in satellite products?

Monitoring water bodies using spectral remote sensing data

- Spectral datasets allow for clear discrimination of water column components.
- Data available from a variety of sensors at different spectral resolutions.

Machine learning based spectral inversion framework

Machine Learning (ML) tools commonly used for the estimation! of Water Quality Indicators (WQI) from remote sensing reflectance (*Rrs*).

- § **Mixture Density Networks (MDN)1**
- § Bayesian Neural Networks with MC-dropout (BNN-MC)2
- § eXtreme Gradient Boosted Trees (XGB)3
- § Support Vector Machines/Regression (SVM)4

I ML approaches show excellent WQI estimation on available I labeled datasets.

¹ MDN References Pahlevan et al. 2020, Smith et al. 2021,

O'Shea et al. 2021, Pahlevan et al. 2022

² BNN-MC References Werther et al. 2022

³ xGB References Cao et al. 2020

⁴ SVM References Kwiatkowska et al., 2003, Zhan et al. 2003

The need for uncertainty

- ML models function as black boxes
	- Performance only guaranteed for test samples like the training samples.
	- For practical applications need a way to identify Out-of-distribution (OOD) samples.
- Sources of uncertainty in ML
	- § *Aleatoric* (or random) uncertainty
	- *Epistemic* (or knowledge based) uncertainty

TASK: Estimate f(x) such that it minimizes the mean squared error:

argmin, $(1/N)||y - f(x)||^2$ **SCORE**

Mixture Density Networks (MDNs)

- Neural network variant that estimates the output as mixture of Gaussians.
	- The Gaussians are chosen to maximize the probability of the expected output for the training samples.
	- Designed for scenarios wherein the output distribution is expected to be multimodal.

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TensorFlow

Uncertainty Estimation for MDNs⁵

Since the MDN output is probabilistic in nature, the uncertainty can be estimated from the predicted distribution:

$$
\sigma_{UNC}^2 = \mathbb{V}(y_i|x_i) = \sigma_{alt}^2(x) + \sigma_{eps}^2(x)
$$

- § Prediction uncertainties have been shown to be well approximated by the variance of the estimated distribution.
- § Further, the variance can be decomposed in aleatoric and epistemic components. **⁵ MDN-uncert References**

9

$$
\sigma_{UNC}^2 = \mathbb{V}(y_i|x_i) = \sigma_{alt}^2(x) + \sigma_{eps}^2(x)
$$

$$
\sigma_{UNC}^2 = \mathbb{V}(y_i|x_i) = \mathbb{E}_{k \sim \pi}(\mathbb{V}(y|x,k) + \mathbb{V}_{k \sim \pi}(\mathbb{E}(y|x,k))
$$

Key:

- x_i : Remote Sensing Reflectance
- y_i : Water optical parameters
- σ: standard deviation
- π_i : likelihood of the ith MDN component
- μ_i : mean of the ith MDN component
- Σ_i : variance of the ith MDN component

K $\sum_{j=1}^{n} \pi_j(x) \left\| \mu_j(x) - \sum_{k=1}^{n} \pi_k(x) \mu_k(x) \right\|$ $\sum \pi_j(x) \Sigma_j(x)$ + aleatoric epistemic

10

Sample MDN estimated uncertainties

- High confidence samples
	- Distribution appears unimodal.
	- Low variance in individual components.

- Low confidence samples
	- Distribution appears to have many well-separated modes (peaks).
	- Components with a very large spread (variance) indicating model uncertainty.

GLORIA⁶: A Large (N=~8,237) Globally Distributed In situ Dataset for training and testing the MDNs

In situ **measurements**

⁶ GLORIA Lehmann et al. (2023)

GLORIA⁶: A Large (N=~8,237) Globally Distributed In situ Dataset for training and testing the MDNs

• Contains samples over ~3-4 orders of magnitude concentration range

13

Validate the estimated uncertainty

- The MDN uncertainty metric successfully identifies unexpected data conditions, such as:
	- § Noisy Test Data
	- § Noisy Training Data
	- § Out-of-Distribution samples
	- § Atmospheric Distortion
- The uncertainty metrics also show a clear correlation between the error and uncertainty.
	- Allows the use of uncertainty as a proxy for error in some cases.

Even for satellite data can qualitatively verify that prediction uncertainty is related to test-training similarity. ¹⁴ **from Saranathan et al, 2022 (TGRS).**

MDN estimated Chl*a* **and associated uncertainty maps over near concurrent measurements over San Francisco Bay**

Interpret the MDN estimated uncertainty metric

March 4th, 2017

- The MDN uncertainty metric while valuable is **hard to interpret**
	- The scale of the metric is based on properties of the model.
	- Understanding/Interpreting the maps takes identification of a map-specific scaling.
	- The scale of the original metric is not intuitive.

• Need to modify/calibrate the metric to make it "human-friendly".

MDN estimated WQI products and associated (unscaled) uncertainty maps from OLCI data over Chesapeake Bay.

Calibrate the estimated uncertainty for human interpretability

- Identify a simple multiplicative factor based on the predicted value to map the uncertainty into a usable space.
- The calibration translates the uncertainty to the same space as the predicted values making interpretation more intuitive.

Estimate uncertainty for satellite data over Chesapeake Bay: OLCI Data

• Currently, generating scaled and unscaled uncertainty products for many different sensor/spectral resolutions

17

• Showing the OLCI results as a proxy for the expected results on the PACE mission

Acolite-processed imagery

Estimate uncertainty for satellite data over Chesapeake Bay: HICO Data

April 1st, 2010

Product Estimates Unscaled uncertainty Calibrated uncertainty

18

Similar products can also be extracted for hyperspectral data extracted from the HICO sensor

L2GEN-processed imagery

Conclusions

- The MDN uncertainty metric clearly addresses the missing component of confidence associated with the model's prediction.
	- Very useful for identifying unexpected data conditions (noisy/distorted data or OOD samples).
	- Clear correlation between error and MDN estimated uncertainty.
- The calibration technique appears to make the estimated uncertainty metric more intuitive for the end-users.
	- *Operational Caveat*: Most of the model creation and validation is performed using low noise *in situ* data and statistical guarantees may not extend to satellite data products.

Future Work

- Uncertainty Estimation
	- Compare the [MDN-specific](mailto:arun.saranathan@ssaihq.com) uncertainty estimates to estimates from c BNN-MC, ensemble of MLP's, etc..
	- Identify/isolate the main factors affecting the amount of uncertainty s
- Uncertainty Metric Calibration
	- Experiment with other non-interval based methods for uncertainty cal
	- Include end-user suggestion into the calibration process to generate the
- For any questions/comments or general interest, arun.saranathan@ssaihq.com

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Additional Slides

MDN model prediction performance for WQI
MDN Test Perfromance-S3A

MDNs perform admirably on indistribution test samples for many different sensors.

> Showing results @ PACE proxy OLCI (S3A) and HICO resolutions.

Effect of noise on MDN performance and uncertainty

The uncertainty metric is clearly able to track the presence of increased noise in the test samples. Further the increase in uncertainty also corresponds to a decrease in the MDNs prediction performance.

Effect of OOD samples on MDN performance and uncertainty

The uncertainty metric is clearly able to track the presence of OOD samples. Clearly, the uncertainty increases when the distance of the test samples from the training samples increases.

Uncertainty Metric dependance on Data

- The estimated uncertainty metric for samples in specific Chl*a* ranges clearly seems to depend on the number of training samples present in that range.
- The uncertainty metric scale seems very different from the predicted values.

Uncertainty correlation with predicted error

• Even for medium-resolution multispectral sensors there is clear correlation between error and uncertainty

MDN Model properties and Hyperparameters

Data Preprocessing:

Rrs: intra-quartile scaling **WQI:** Log-Scaling + MinMax scaling [-1, 1]

Missing value have no effect of the estimated gradient.

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